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# GCAN-203

Bluetooth -CAN converter

User manual



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# 1. Introduction

## 1.1 Overview

GCAN-203 has a standard CAN-Bus interface. GCAN-203 can send CAN-Bus data to other equipment with Bluetooth.

## 1.2 Properties at a glance

- CAN-Bus baud rates range from 5Kbps to 1Mbps
- CAN-Bus isolation module insulation voltage: DC 1500V
- Maximum data traffic: 300 frames per second
- Bluetooth using 2.0
- Power supply: 9~30V (20mA, 24V DC)
- Installation method: DIN rail
- Working temperature range: -40 °C ~ +85 °C;
- Size: (L) 112mm \* (W) 70mm \* (H) 25mm.

# 2. Installation

GCAN-203 interface shown in figure 2.1.



Figure 2.1 GCAN-203 interface definition

## 2.1 Power connection and indicator status

GCAN-203 recommends using standard 24V power supply. GCAN-203 has three indicator lights, 1 PWR, 1 SYS, 1 CAN. The functions of the three indicators are shown in table 2.2, the indicators in different states, the converter status shown in table 2.3.

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<b>LED</b>	<b>Color</b>	<b>Indicates the status</b>
PWR	Green	Power indicator
SYS	Green	Bluetooth connection indication
CAN	Red/Green	CAN status indication

Table 2.2 GCAN-203 Indicators

<b>LED</b>	<b>Status</b>	<b>Indicates the status</b>
PWR	On	Power is normal
	Off	Power is not normal
SYS	Blinking	No equipment connected
	Slow blinking	Equipment connection is successful
CAN	Blinking red	CAN communication error
	Blinking green	CAN communication is normal

Table 2.3 GCAN-203 indicator status

### 3. CANBlue config software

#### 3.1 Configuration

Disconnect the GCAN-203 power supply. We can connect to GCAN-203 and computer with USB. When GCAN-203 is configuring, no external power is required.

GCAN-203 factory setting: CAN-Bus baud is 250K, working mode is normal mode, name is SN number, password is 1234.

#### 3.2 Software connection

Open "CANBlue Config" software in the "②CANBlue 模块配置软件" document to configure the converter. Click "Connect" to connect the converter. The connection is shown in figure 3.1.

You can click "UpLoad" to upload the parameters in the converter to your computer.

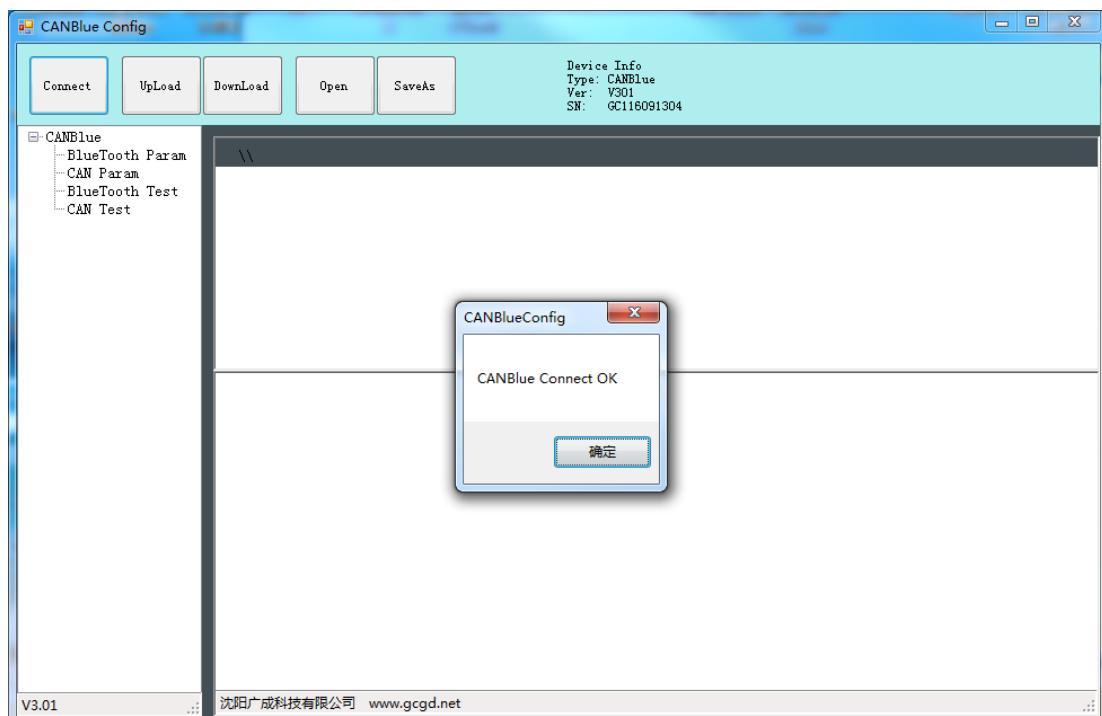


Figure 3.1 CANBlue Config software interface

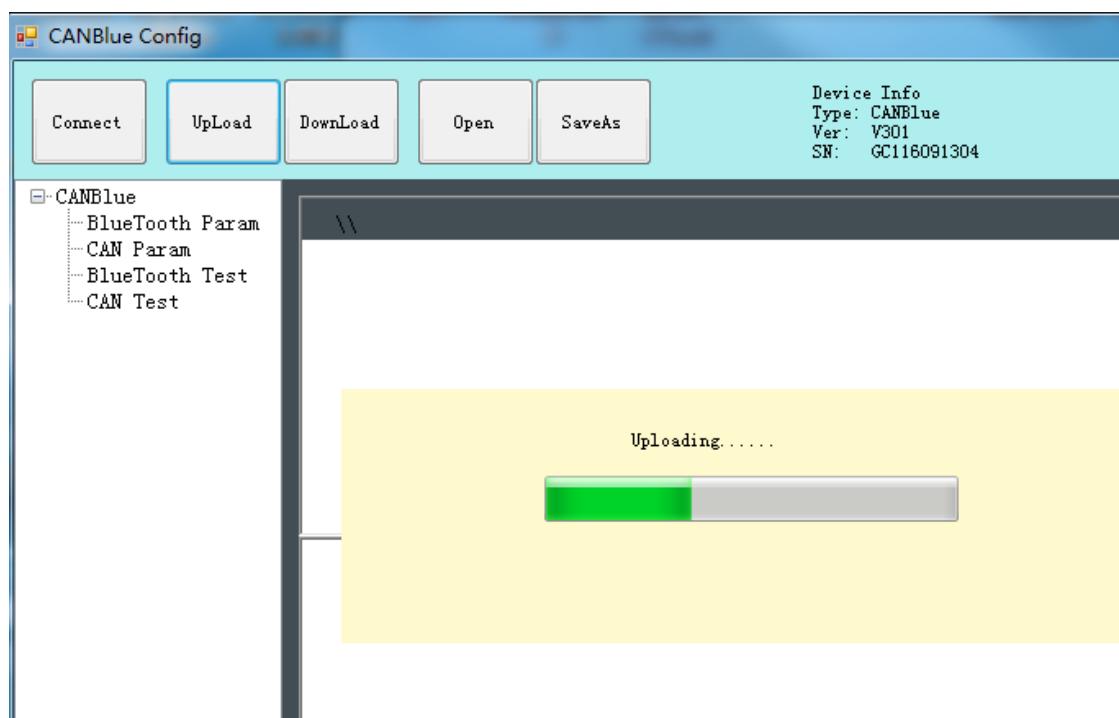


Figure 3.2 CANBlue Config software upload parameters

### 3.3 CAN parameter setting

Click "CAN Param" to enter CAN communication parameter setting. We can click "CAN Baud" to configure the baud rate of the CAN-Bus, as shown in the following

table.

Parameter	Baud rate	Parameter	Baud rate
0	1000K	1	800K
2	666K	3	500K
4	400K	5	250K
6	200K	7	125K
8	100K	9	80K
10	50K	11	40K
12	20K	13	10K
14	5K		

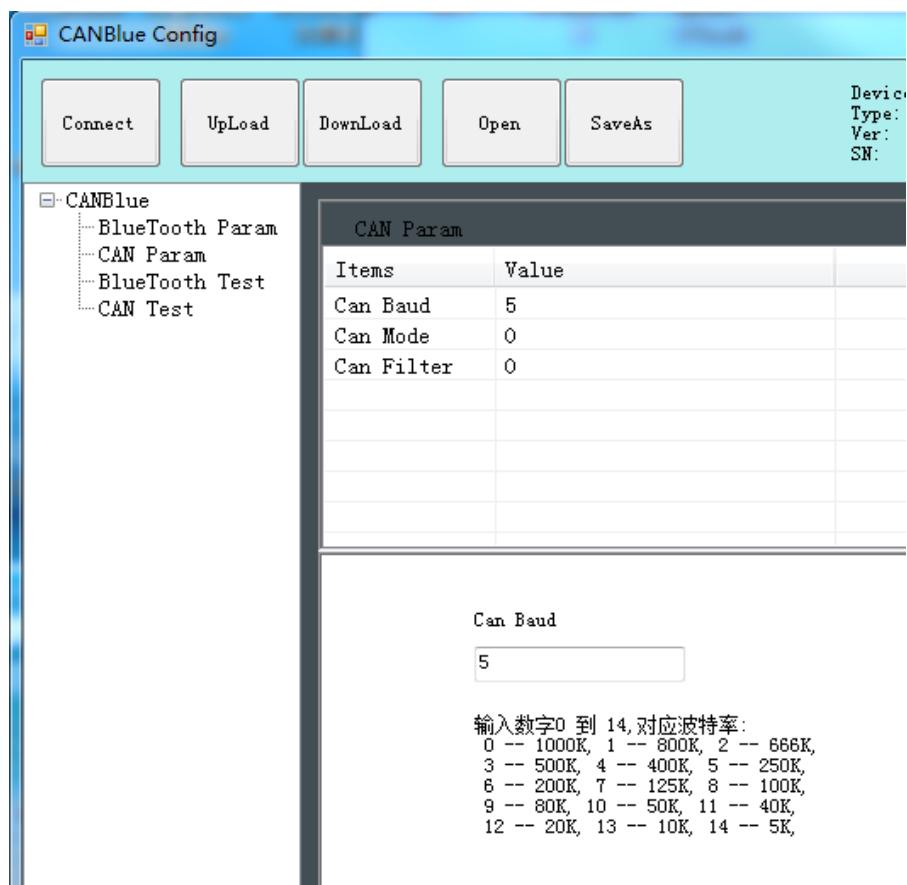


Figure 3.3 CAN baud rate setting

The default value of “CAN Mode” or “CAN Filter” is set to 0, and please do not change it.

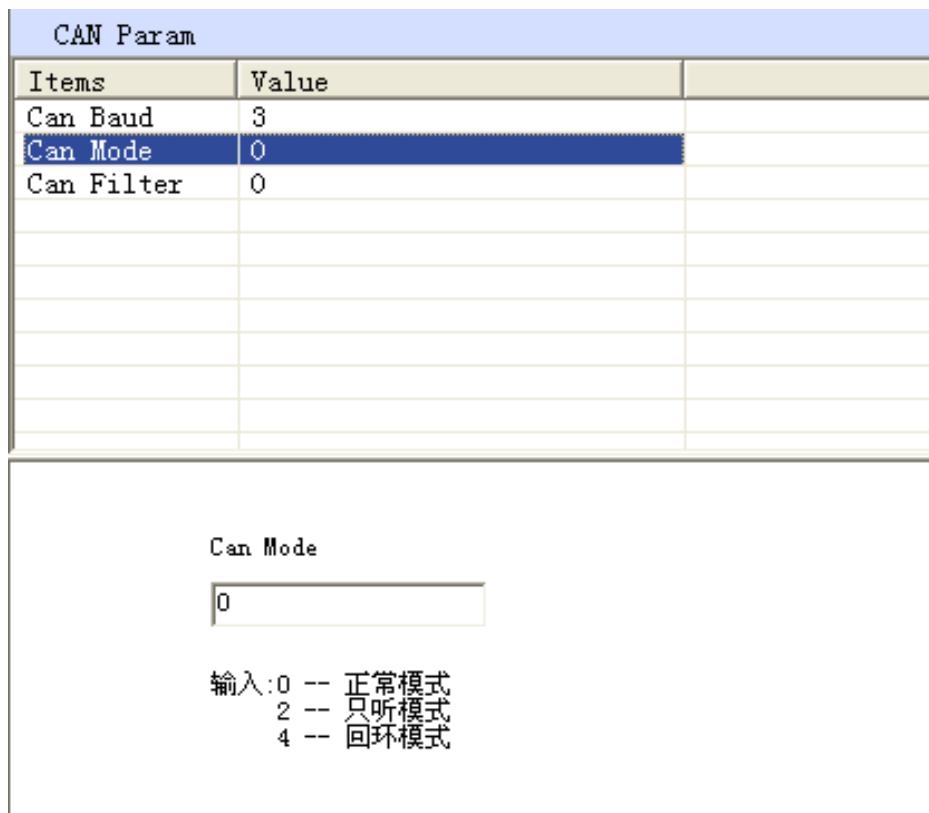


Figure 3.4 CAN operating mode setting

### 3.4 Bluetooth parameter settings

Click "Bluetooth Param" to enter the Bluetooth parameter settings.

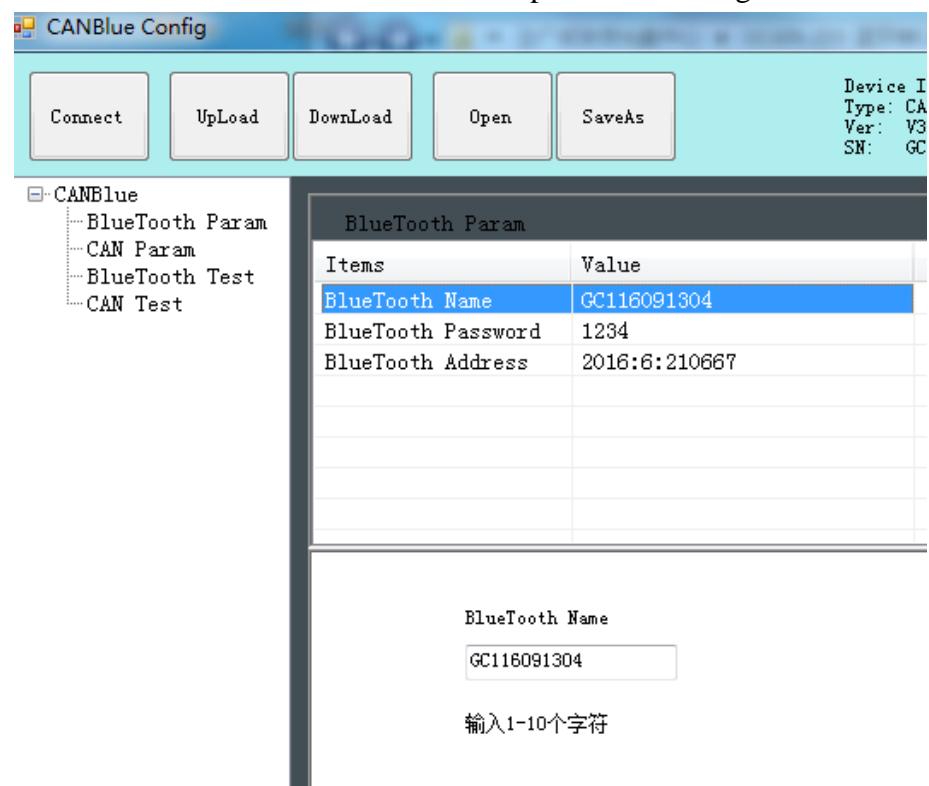


Figure 3.5 Bluetooth settings

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The user can set the GCAN-203's name and connection password. GCAN-203's default name is SN number, password is 1234.

### 3.5 End of configuration

Click "Download" to write the configuration data to the converter's flash, as shown in figure 3.6.

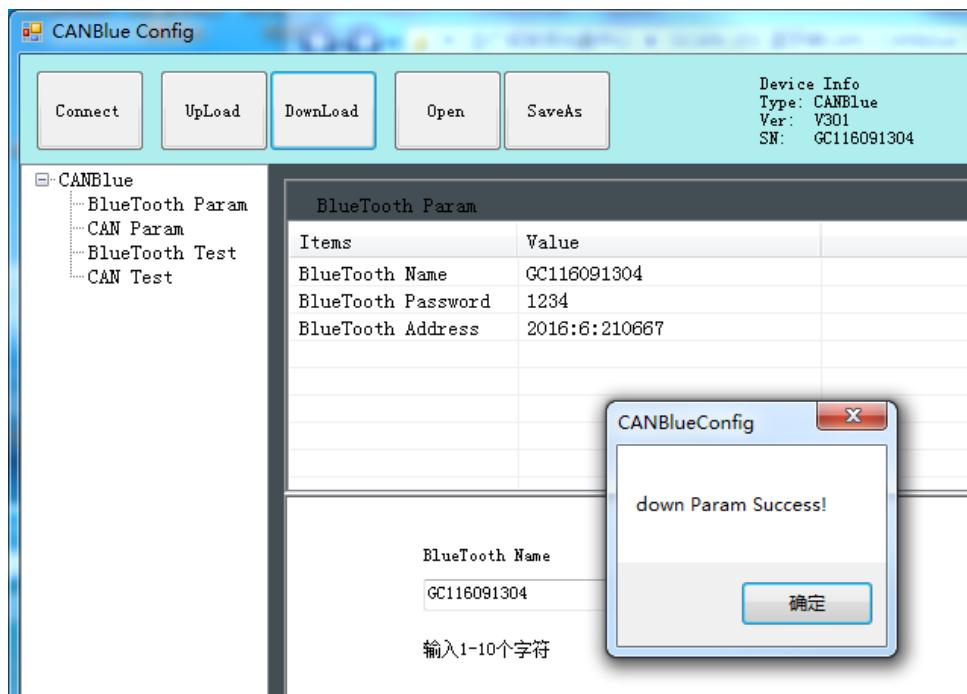


Figure 3.6 Download successful

The pop-up dialog displays "download Param success". Then power-on again. The new configuration can take effect.

**Note: The converter must be power-on again, otherwise the configuration will not take effect.**

### 3.6 Save the configuration file

Click "SaveAs" to save the configuration parameters to the PC. The file can be opened again.

### 3.7 Open the configuration file

Use the "OPEN" function to open the configuration file and modify it. Then you can click DownLoad to the converter that the new configuration can be saved.

**Note: The working mode of "BlueTooth Test" and "CAN Test" is used for testing . These functions cannot be used.**

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## 4. Application examples

### 4.1 Equipment wiring

GCAN-203 uses 9-30V DC power supply.

Connect CAN\_H to CAN-Bus CAN\_H, CAN\_L to CAN-Bus CAN\_L. A High-speed CAN bus must be terminated on both ends with 120 Ohms. Otherwise disturbances may arise.



Figure 4.1 The wiring diagram of GCAN-203

As shown in figure 4.1, the left side of the equipment is USBCAN-II Pro. Wiring and termination resistance must be confirmed correctly. Open USBCAN-II Pro equipment with ECANTools software, then select the baud rate to 250K.

### 4.2 Bluetooth connection

Install "CANBlue.RSO.apk" APP to a mobile phone with android which is in the "③ 安卓系统串口助手安装包" document. Search for Bluetooth equipment, then enter the connection password.

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## 4.3 Bluetooth serial assistant use

### 4.3.1 Connect to GCAN-203

Open the software, the interface is shown in figure 4.2. The function of the four buttons will be shown here:

蓝牙开关——Turn on Bluetooth or turn off Bluetooth.

搜索设备——Click “搜索设备” .You can find all the converters that opened Bluetooth, only the converter name turn blue can be connected. (GCAN-203's default name is SN number, password is 1234)

版本升级——Not open yet.

侦听连接——Not open yet.

Enter the receive / send data interface, as shown in figure 4.3.



Figure 4.2 Software interface



Figure 4.3 Main interface for sending and receiving data

#### 4.3.2 Send and receive data for example

The following is a brief introduction to the received / sent data format. Please refer to the **appendix** for detailed data format.

Data description	For example
CAN Frame Information (FF、RTR)	0
CAN Frame Information (DLC)	8
CAN Frame ID	00 00 07 00
CAN Frame Date	11 22 33 44 55 66 77 88

The CAN frame Information(FF, RTR) represents the frame format and frame type of the CAN frame. The specific values are shown in the following table; the CAN frame Information (DLC) represents the byte length of the CAN frame data. According to the actual needs , it fills 0 to 8.

Example of special data transmission: table 4.1.

- 1.The mobile equipment sends data to the CAN terminal, DLC is 2 bytes less than 8 bytes of data(11 22 33 44 55 66 77 88), CAN receives 2 bytes of data (11 22).
- 2.The mobile equipment sends data to the CAN terminal, DLC is 8 bytes more than 4 bytes of data(11 22 33 44), CAN receives 8 bytes of data (11 22 33 44 XX XX XX)

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XX)(XX is used for the filling, which is meaningless).

3.CAN sends data to the mobile equipment, and CAN terminal sends 4 bytes of standard data frame (11 22 33 44). The mobile equipment receives 8 bytes of frame data (11 22 33 44 XX XX XX XX)(XX is used for the filling, which is meaningless).

	<b>Data transfer direction</b>	<b>Data</b>
<b>1</b>	The mobile equipment is sender	02 00 00 00 08 11 22 33 44 55 66 77 88
	CAN is receiver	Data length 2 bits, Frame ID: 008 Frame data: 11 22
<b>2</b>	The mobile equipment is sender	08 00 00 00 08 11 22 33 44
	CAN is receiver	Frame ID: 008 Frame data: 11 22 33 44 XX XX XX XX
<b>3</b>	CAN is sender	Data length 4 bits, frame ID: 008, Frame data: 11 22 33 44
	The mobile equipment is receiver	04 00 00 00 08 11 22 33 44 XX XX XX XX

Table 4.1 Example of special data transmission

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## 5. Technical specifications

Connection	
<b>CAN interface</b>	Phoenix connector
Interface characteristics	
<b>CAN interface</b>	ISO 11898 standard, CAN2.0A/B
<b>CAN baud rate</b>	1000K, 500K, 250K, 200K, 125K, 100K, 50K
<b>Electrical isolation</b>	1500V, DC-DC
<b>CAN terminal</b>	Need additional installation
Wireless parameters	
<b>Bluetooth</b>	Bluetooth 2.0
Power supply	
<b>Supply voltage</b>	+9~30V DC
<b>Supply current</b>	30mA
Environmental testing	
<b>Working temperature</b>	-40°C~+85°C
<b>Working humidity</b>	15% to 90% RH, no condensation
<b>EMC test</b>	EN 55024:2011-09 EN 55022:2011-12
<b>Protection grade</b>	IP 20
The basic information	
<b>Outline size</b>	112mm *70mm *25mm
<b>Weight</b>	100g

## Appendix: GCAN-203 data flow definition

## Bluetooth→CAN-bus data flow definition

A CAN frame contains 13 bytes.



CAN frame, For example, type or length of the CAN frame, and so on.

BIT7

BITO



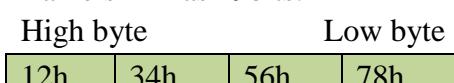
**FF:** Identifier for standard and extended frames, 1 means extended frame, 0 means Standard frame.

**RTR:** Remote frame and data frame identification bit, 1 means extended frame, 0 means Standard frame.

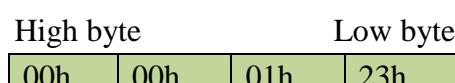
**Reserve:** Retention value is always 0.

**B3~B0** : Data length. Identifying the data length of the CAN frame.

Frame ID. Its length is 4 bytes. Standard frame's ID has 11 bits; extended frame's ID has 29bits.

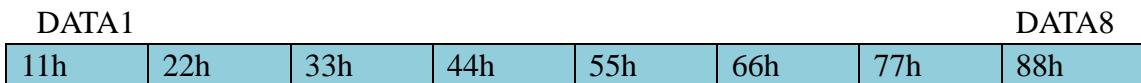


## Representation of extended frame ID 0x12345678

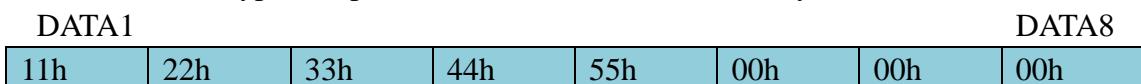


## Representation of standard frame ID 0X123

Frame data. Its length is 8 bytes. The effective length is determined by the B3~B0 value of the frame information.



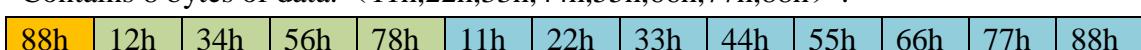
The above is a typical representation of data, which has 8 bytes.



The above is a typical representation of data, which has 5 bytes.

### **Example:**

The following example is an extended data frame, Frame ID is 0x12345678, Contains 8 bytes of data. (11h.22h.33h.44h.55h.66h.77h.88h) .



**Note:** each frame is fixed to 13 bytes. If it is less than 13, the empty parts will be written with 0. Otherwise it will lead to communication error.

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## Sales and service

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